Dispersion Engineering and Low-Loss Optimization of Footprint-Efficient and Rotationally Asymmetric Resonators

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Universal Blueprint for Intuitive Resonator Design

The Limitations of Integration

The large footprint of low free spectral range (FSR) resonators has limited the integration of systems for broadband technologies such as LiDAR, microwave synthesis, and 5G, which require GHz repetition rates to interface with the microwave domain. FSR depends on both group index and resonator path length. However, since high ng usually introduces high losses, it is more straightforward to maximize the **resonator path length per chip surface area.** To this end, many have explored wrapping waveguides over very small areas on chips, leading to radially asymmetric resonators.



same path length, smaller footprint?



Challenges of Waveguide Bends with Non-Constant Curvature

Microring resonators are one of the most common photonics cavities as they possess a convenient rotational symmetry that allows them to be represented by the effective 2D model, for computationally-efficient simulations. By writing $E(r, \theta, z) = A(r, z) exp(im\theta)$, one need only solve for A(r, z). For structures with non-constant curvatures, however, there is currently **no effective way to** capture their dynamics aside from full 3D **simulations**, which are very time consuming.



Challenges of Waveguide Bends with Non-Constant

Curvature

We develop a framework for unraveling any arbitrary bend into an effective straight waveguide system with effective geometric and material properties, opening the door for intuitive design and simulation of previously inaccessible resonator structures.

Unravel

A Tale of Two Transformations



DCTO Design Guidelines for Low-Loss Racetracks

Z-plane

Half Circle

y (μm)

DCTO Applied The bend of a racetrack can be segmented into infinitesimally small path lengths to apply the transformation differentially, as for each differential path length ds, an instantaneous R(s) can be defined. Effective waveguide width h' will change depending on original width *h* and as a function of path length.



Bezier Curve

Euler Bend

DCTO Design Guidelines for Eliminating Avoided Mode Crossings (AMX)

Quantifying AMX

Frequency = 270 THz

 $h'(s) = |R(s)\ln\frac{R(s) - h}{R(s)}|$

DCTO Equations



$$P_{1,2} \propto \int_{S} \varepsilon E_1 \cdot E_2^* \,\mathrm{d}S$$



The non-orthogonality of higher order modes is another consequence of shifted mode profiles caused by geometric bending. This results in a non-zero overlap between these modes, allowing them to couple and transfer power.

Experimental Observation



